Handling item non-response in Structural Equation Modelling with ordinal variables



I. Framework

• Ordinal variables (items), cross-sectional data, N independent observations. Structural equation modelling (SEM)

Let y be the vector of ordinal items of dimension p, η the vector of factors, and y_i^{\star} the underlying continuous variable of the ordinal variable y_i , where $y_i = a \Leftrightarrow au_{i,a-1} < y_i^\star < au_{i,a}, i = 1, \dots, p$, a is the a-th response category of variable y_i , $a = 1, \ldots, c_i$, $\tau_{i,a}$ is the *a*-th threshold, $\tau_{i,0} = -\infty$, and $\tau_{i,c_i} = +\infty$.

$$\mathbf{y}^{\star} = \boldsymbol{\nu} + \Lambda \boldsymbol{\eta} + \boldsymbol{\varepsilon}$$

 $\boldsymbol{\eta} = \boldsymbol{\alpha} + B \boldsymbol{\eta} + \boldsymbol{\zeta}$,

where $\boldsymbol{\nu}$ and $\boldsymbol{\alpha}$ are intercept vectors, $\boldsymbol{\varepsilon} \sim \mathcal{N}_p(\mathbf{0}, \Theta_{\varepsilon})$, $\boldsymbol{\zeta} \sim \mathcal{N}_q(\mathbf{0}, \Psi)$, $Cov(\boldsymbol{\eta}, \boldsymbol{\varepsilon}) = 0$ $Cov(\eta, \zeta) = Cov(\varepsilon, \zeta) = 0, I - B$ is non-singular, and I is the identity matrix. Let θ be the model parameter vector; it includes ν , α , Λ , B, Θ_{ε} , Ψ , τ . • Item non-response (at least one variable observed in each sample unit) Any type of missing pattern (monotone/ non-monotone) is allowed.

2. Background information on estimation

- Maximum likelihood is computationally unfeasible for SEM with ordinal items.
- Conventional estimation approach: three-stage diagonally weighted least squares (DWLS).
- When data are missing at random (MAR) (Rubin, 1976) multiple imputation followed by DWLS (MI-DWLS) is recommended.
- Alternative estimation approach: **pairwise likelihood** (**PL**),

$$pl(\boldsymbol{\theta}; \mathbf{y}) = \sum_{n=1}^{N} \sum_{i < j} \log f(y_{ni}, y_{nj}; \boldsymbol{\theta}), i, j = 1, \dots, p.$$

In SEM with ordinal variables a bivariate probability is modeled as

$$\pi\left(y_{ni}=a, y_{nj}=b; \boldsymbol{\theta}\right) = \int_{\tau_{i,a-1}}^{\tau_{i,a}} \int_{\tau_{j,b-1}}^{\tau_{j,b}} f\left(y_i^{\star}, y_j^{\star}\right) dy_i^{\star} dy_j^{\star}.$$

2.1 Treatment of missing values under PL

• The complete-pairs PL (CP-PL) defined as

 $pl^{CP}(\boldsymbol{\theta};\mathbf{y}) = \sum_{n=1}^{N} \sum_{i < j} \tilde{r}_{n,ij} \log f(y_{ni}, y_{nj}; \boldsymbol{\theta}),$

where $\tilde{r}_{n,ij}$ takes the value 1 if both y_{ni} , y_{nj} are observed and 0 otherwise. • The available- case PL (AC-PL) defined as

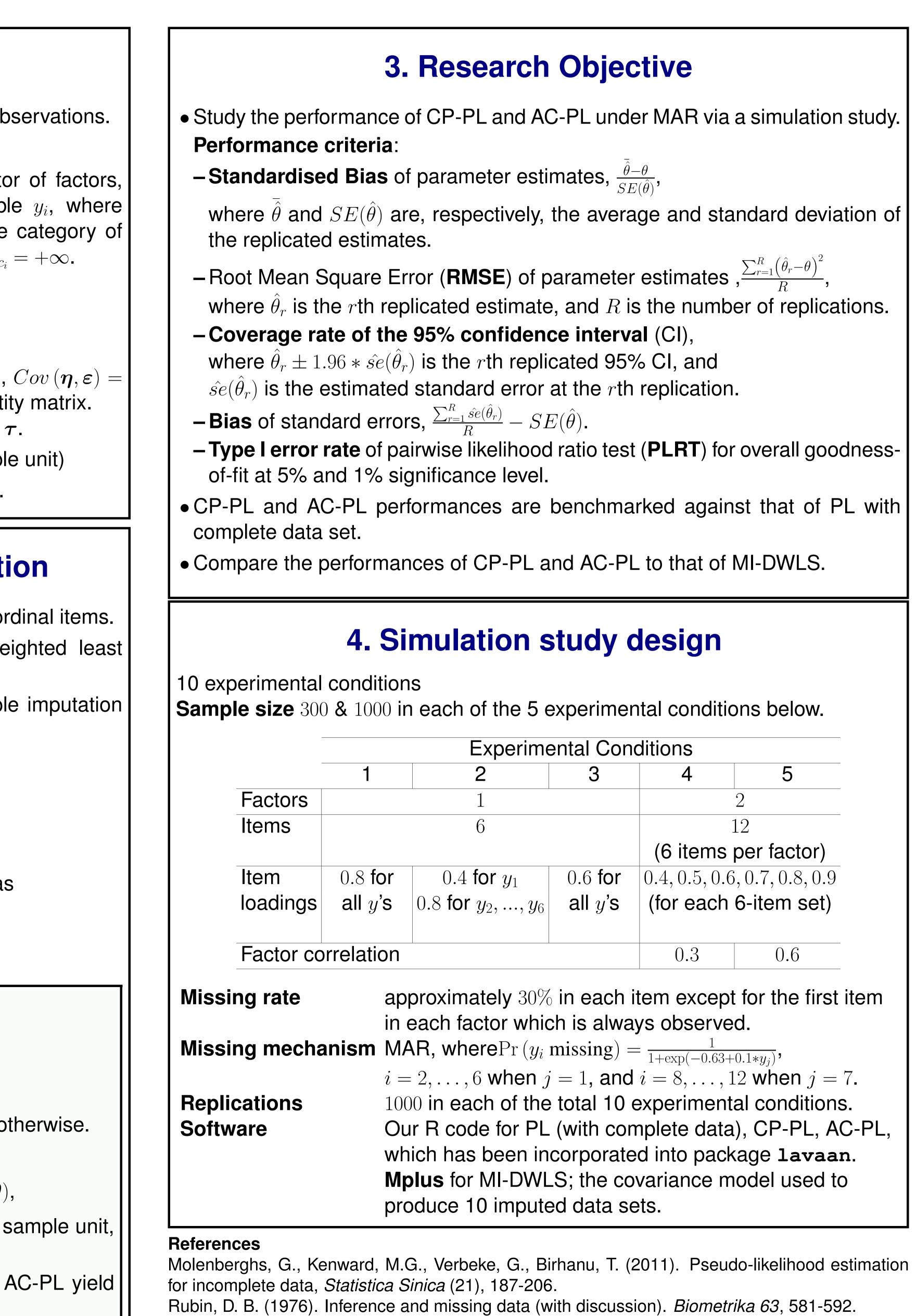
$$pl^{AC}(\boldsymbol{\theta}; \mathbf{y}) = pl^{CP}(\boldsymbol{\theta}; \mathbf{y}) + \sum_{n=1}^{N} m_n \sum_{i=1}^{p} r_{ni} \log f(y_{ni}; \boldsymbol{\theta})$$

where m_n is the number of items with missing value for the nth sample unit, and r_{ni} takes the value 1 if y_{ni} is observed and 0 otherwise.

• Molenberghs et al. (2011) argue that, in general, CP-PL and AC-PL yield biased estimators under MAR.

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Rubin, D. B. (1976). Inference and missing data (with discussion). *Biometrika 63*, 581-592. Acknowledgments: Many thanks to Prof. Yves Rosseel who incorporated our R code into his R package lavaan. The research is supported by ES/L009838/1 ESRC grant.

(6 items per factor)		
.9		
(for each 6-item set)		
)		

approximately 30% in each item except for the first item

i = 2, ..., 6 when j = 1, and i = 8, ..., 12 when j = 7. Our R code for PL (with complete data), CP-PL, AC-PL, which has been incorporated into package lavaan.

5. Simulation results

Loadings and factor correlation

- coverage rate than MI-DWLS.
- criteria.
- but this is the case in PL with complete data as well.
- rate.

Thresholds

- No clear preference between AC-PL and CP-PL as:

PLRT for overall goodness-of-fit

- levels 5% and 1% with two exceptions:
- nominal levels, and
- actually this occurs in PL with complete data as well.

- indices to judge overall fit.
- pared it to CP-PL and AC-PL.

• All three methods, CP-PL, AC-PL, and MI-DWLS, show acceptable performance regarding all performance criteria in all conditions.

However, CP-PL and AC-PL exhibit lower standardised bias and a better

• CP-PL and AC-PL exhibit standardised bias and coverage rate fairly close to those of **PL with complete data**, especially for sample size 1000.

• A sample size increase seems to be associated with better performance in all

• A smaller factor **loading for** y_1 which determines the level of MAR, seems to be associated with slightly larger bias of both estimates and standard errors

• Smaller **loadings** in all items seem to be associated with larger RMSE.

• A higher factor correlation seems to be associated with improved coverage

• MI-DWLS clearly outperforms CP-PL and AC-PL in all criteria.

-AC-PL exhibits acceptable standardised bias (average per condition up to 11%), while standardised bias in CP-PL may exceed 40%.

-But, AC-PL systematically under-estimates the standard errors leading to unacceptable coverage rate. CP-PL shows similar levels of standard errors bias as MI-DWLS and acceptable coverage in most occasions.

• A hybrid PL, which uses the AC-PL threshold estimates and the corresponding CP-PL standard errors, exhibits acceptable coverage rate in all conditions.

Both CP-PL and AC-PL show rates of Type I error very close to the nominal

-in Ex. Con. 6 with sample size 300, where the rates are smaller than the

-in Ex. Con. 3, where the rates are a bit larger than the nominal ones, but

6. Discussion

• The general result that CP-PL and AC-PL yield biased estimates do not seem to hold in SEM, especially for loadings and factor correlations.

• Potential advantages of CP-PL and AC-PL over MI-DWLS: a) MI-DWLS requires a model for imputing, b) in MI-DWLS, it is no clear how to use the fit

• Worthy to develop a doubly-robust PL (Molenberghs et al., 2011) and com-